



Nano Packaging Technology for Interconnect and Heat Dissipation

NANOPACK

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WORK PACKAGE 1 : Systems and applications specifications

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Decision on material pairings and geometrical set-up for test-specimens and test systems

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WORK PACKAGE 1 : Systems and applications specifications

TASK 1.2
Decision on material pairings and geometrical set-up for
test-specimens and test systems

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WORK PACKAGE 1 : SYSTEMS AND APPLICATIONS SPECIFICATIONS

TASK 1.2 Decision on material pairings and geometrical set-up for test-specimens and test systems

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1 ABBREVIATION / DEFINITION

TIM	Thermal Interface Material
SOI	Silicon On Insulator
CNT	Carbon Nano Tube
BLT	Bond Line Thickness
MCM	Multi-Chip Module
LCC	Life Cycle Cost
SCM	Single-Chip Module
R _{th}	Thermal Resistance
HP	Heat Pipe
BN	Boron Nitride
PAO	Poly Alpha Olefins
PDMS	Poly Dimethyl Siloxans
RTD	Resistive Thermal Device
NP	Nano Particles
SEB	Seat Electronic Box

2 INTRODUCTION

This deliverable defines the final decision of the consortium members about the material pairings used in TIM materials, and about the test specimen and test systems used in the final evaluation of the TIM materials that will have been developed in the NANOPACK project.

TIM material testing has three significantly different applications. On one hand TIM quality has to be checked during the material development phase. For this purpose experimental methods are needed, that can be lengthy and complicated, but need to be very accurate. On the other hand standardized industrial methods are needed to compare the quality of the TIM material of different TIM vendors to qualify them for certain applications. The standardized methods have to be able to qualify on one hand again the TIM material in itself, on the other hand methods are needed to verify and compare the quality of the TIM in real life applications [1]. These are called in our document the "in situ" measurements.

In the NANOPACK project we will develop methodologies and test structures both for the experimental and the industrial methods, this explains the diversity of the test structures that are aimed to be developed in WP4 of the NANOPACK project.

The statements of this deliverable are the result of the first 3 months research of the individual consortium partners, discussed in details at the first WP4 meeting at 21/01/2008 Budapest.

The decision about material pairings for particle filled materials is presented in Chapter 3.

Chapter 4 defines the final decision of the partners about the various geometrical set-ups for test specimen used in the different testing methods.

The final demonstrators are presented in Chapter 5.

3 DECISION OF MATERIAL PAIRINGS

In the framework of the NANOPACK research the following material pairings will be used for particle filled materials:

Matrix material viscosity at 40C: >20 cSt

Common thermal grease oils:

Hydrocarbon based: PAO (poly alpha olefins),
 Silicone based: PDMS (poly dimethyl siloxane)
 Thermal pad
 Phase change materials

Thermal and electrical adhesive:

Matrix: silicone elastomers (more flexible for improved cycling) and epoxies (stronger adhesion with poor cycling)

Particle systems:

Size range: <20um
 Bi or Tri-modal systems preferred
 Electrical materials: Graphite, Silver, CNT, SiC, BN,
 Thermal materials: Aluminum, Aluminum oxide, Graphite,

Dispersants and surfactants:

Steric acid,

COMMENTS:

If too many different materials are used there will be high Kapitza resistances between the many material mismatches in the thermal path.

Need more information on alternative materials:

CNT based systems, Gold nanograss (fill factors, height, adhesion/seed layers...)

Bosch will use commercially available TIM2 materials (to be selected after finishing T2.1) as well as materials developed by project partners in WP2.

Mating surfaces have been selected from current Bosch products:

- Heat sink materials: Copper (milled), Aluminum alloy (die casted, e.g. AlSi8Cu3SF, AlMgSi1, AlSi12(Fe))
- Circuit materials: Copper (etched), Alumina

These surfaces exhibit certain roughness as well as different oxides that will create a certain thermal contact resistance. Our aim is to quantify the contact resistance in dependence of process steps prior to heat sink attachment (e.g. die casting, shot blasting, milling, etc.).

Schematic of possible material pairings for 3ω method and micro Raman scattering (silicon – orange, oxide – green)

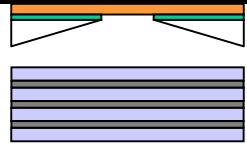
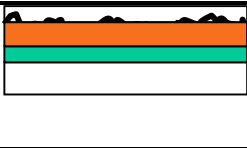
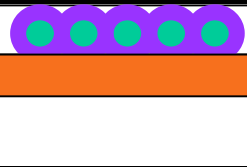
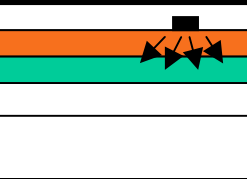
Structures	Impact
	Reference systems, through-plane phonon transmission
	Impact of roughness on thermal characteristics before deposition of nano-particles (NPs)
	Evaluation of pastes with NPs as thermal interfaces.
	Heat dissipation in presence of hot spots.

Table 1 : Schematic of possible material pairings

4 GEOMETRICAL SET-UPS FOR TEST SPECIMEN USED IN THE DIFFERENT TESTING METHODS

4.1 GEOMETRICAL SET-UPS FOR 3-OMEGA AND STEADY STATE TECHNIQUES (*BME, F-IZM, IBM, MICRED, VTT, ICN*)

4.1.1 Geometrical set-up for the 3-omega technique

3 ω -method

Physical dimensions:

Sample width: 5 mm to 20mm

Sample length: 5 mm to 20mm

Sample height: up to 2 mm

Sample thickness: 5 times the thermal penetration depth

Heater/thermometer needs:

For sample thickness greater than 1 μ m (2D heat wave model):

Line width: 5 times smaller than film/sample thickness,

Line length: 20 times longer than film/sample thickness,

For sample thickness less than 1 μ m (1D heat wave model):

Line width: 5 times greater than film/sample thickness,

Line length: 20 times longer than film/sample thickness,

Material for heater/thermometer: Platinum, Nickel, Gold, Molybdenum, Aluminium

4 contact pads bigger than 100 μ m x 100 μ m or alternative 2 rectangular contact pads bigger than 300 μ m x 100 μ m needed for 4-probe measurement set-up

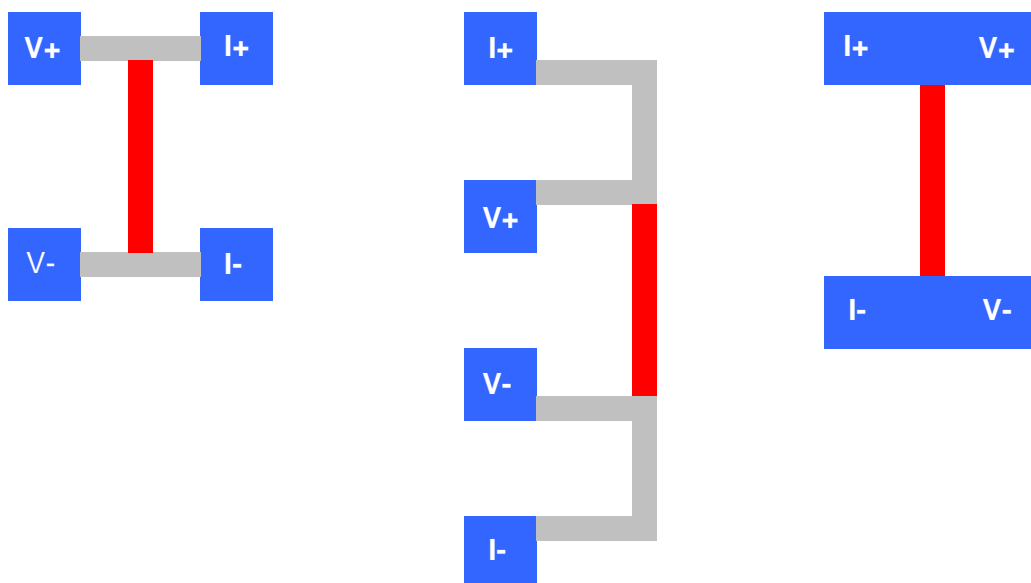


Figure 1: Schematic of possible designs for heater/thermometer (red) and contact pads (blue)

Micro Raman scattering

Physical dimensions:

Sample width: 1 mm to 15 mm

Sample length: 1 mm to 15 mm

Sample height: less than 2 mm

4.1.2 Geometrical set-ups for the steady state techniques

Steady state TIM testing methods may be useful both as experimental methods during material development and methods that may be used for the comparison of TIM material from different producers in a standardized environment.

The versatility of the method explains that steady state methods will be pursued by different partners. The test set-ups of the different partners are presented below.

BME, Micred: Steady-state TIM tester (Figure 2)

Expected specification

Active area:	12.5×12.5 mm ² (or 10×10 mm ²)
Heat flux & temperature measurement	using the same monolithic dice
Heat flux:	max. 20 W (40 W ?) conveyed by Peltier cells
Heat flux accuracy:	± 0.1 W
Resolution of temperature difference measurement	0.006 K
Resolution of TIM R _{th} measurement	0.03 ÷ 0.04 Kmm ² /W
TIM R _{th} measurement	2 ÷ 5 Kmm ² /W ± 5 ÷ 10 %
Mechanical pressure	max. 2·10 ⁵ N/m ²
TIM thickness measurement	optic (?)
Special feature:	symmetric arrangement, reversible heat-flow direction

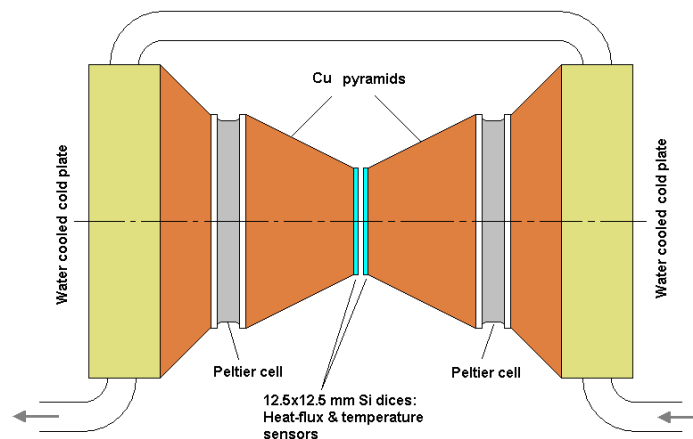


Figure 2: The planned steady-state assembly of BME and MicReD

Testing Methods for IBM microprocessor TIM1 and TIM2 applications

IBM Zurich Research Laboratory will utilize several different test methods to evaluate interface material properties and application performance. Product like test vehicles will be used for demonstrator type performance measurements and research test devices will be used to explore bulk material and particle stack properties. The application test vehicle resembles a typical flip chip packaged Silicon die with heater and sensor array on the opposite side as the TIM and lid/cooler surface as shown in Figure 3.

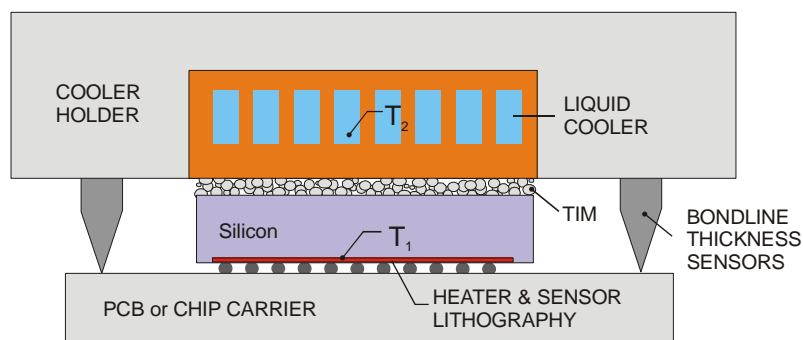


Figure 3 : Flip chip microprocessor TIM1 test vehicle.

Due to the thick silicon chip and variability in cooler performance, this test vehicle is only capable of providing average bondline performance data without localized information on non-uniformities in the bondline due to voids or particle stacking. Heating at the lower surface of the silicon is accomplished using a meandering thin film heater (~30nm gold) with interspersed resistive thermal devices (RTD) also based on meandering serpentine structures with 4-point connections (~30nm thick, 10um wide metal line). This allows a single metallization step to define heater and sensor devices. The typical resistance of a thin film RTD sensor is approximately 150 Ohm with a **sensitivity of 0.5°C/Ohm**. Total thermal resistance or junction-to-air resistance is determined based on the temperature difference between the chip sensors and a set cooler temperature divided by the total power dissipated.

In order to estimate the interface resistance, the thermal resistance of the silicon and water cooler must be known or determined from additional calibration experiments and subtracted from the total resistance (often inducing the largest uncertainty). Inductive based displacement sensors, calibrated to zero before the interface material is applied, track the thickness of the interface as estimated from 4 points along the periphery of the system. Overall accuracy of interface resistance estimation is typically on the order of **+1Cmm²/W**. This test stand can also be used as an application demonstrator when a chip lid is inserted between the chip and cooler surface. With the lid inserted, the effect of a larger TIM2 area can also be investigated.

4.2 TEST STRUCTURE TO INVESTIGATE PACKED PARTICLE ELECTRICAL AND THERMAL INTERCONNECTS (IBM, F-IZM, NANOTEST)

In order to increase the accuracy and area resolution of a thermal test an alternative test system will be developed with the capability to measure both thermal and electrical properties directly at both sides of the interface. This system uses two rectangular sensor chips with RTD sensors directly on both sides of the interface as shown in Figure 4. Heat is introduced below the chip stack by a thin film heater and a cooler is applied to the top of the chip stack. The temperature drop across the interface at specific locations is then measured by the RTD sensors, which have a similar design and performance as the test vehicle shown in Figure 3. In order to measure electrical resistance across the interface, the RTD is replaced by a simple electrode with two contacts and a small current is applied between the upper and lower electrode allowing a 4-point measurement of voltage and current drop across the thin gap. An array of numerous sensors across the interface allows for investigation at locations that are known to have particle stacking non-uniformities such as the center point and along the lines between opposite corners of the square interface area.

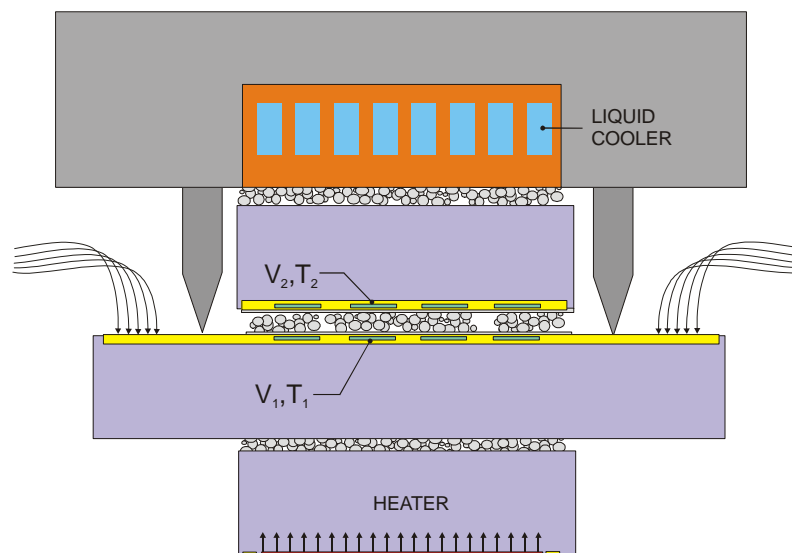


Figure 4: Research test stand for investigation of interface material thermal and electrical properties.

IBM will use the test device shown in Figure 4 with a test chip combination that allows comparison between the region of particle stacking ("x" between chip corners) and the non-stacking or bulk regions. Preliminary results have already shown the test stand is capable of resolving small differences in temperature and electrical gradient between the two regions.

4.3 THIN FILM MICRO-SCALE HEATER/SENSOR DEVICES (TRT, IEMN, CHALMERS, F-IZM)

Contribution of IZM

The principal sketch of the test-system is given below. Its main task is to provide a method for accurate, yet reproducible determination of thermal conductivity and interface resistance of the thermal interface materials under research. The challenge for the test-systems is their need to be compatible with the materials and processes developed in the project.

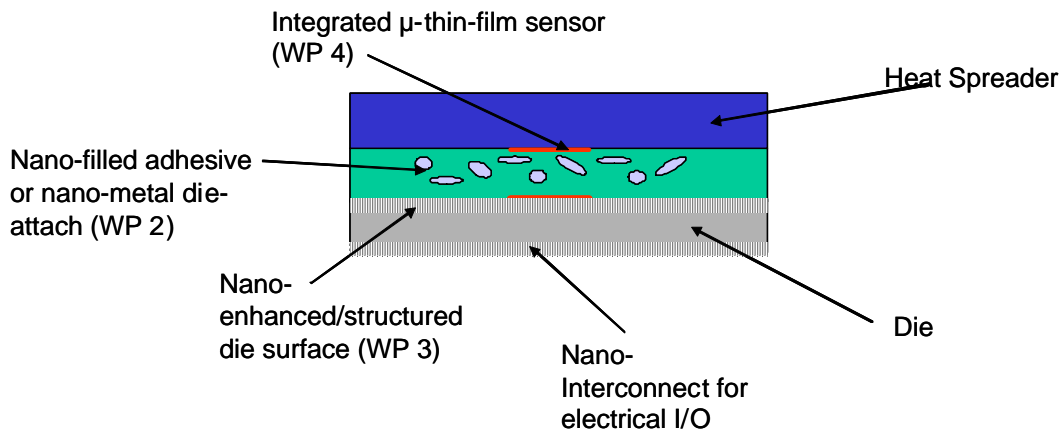


Figure 5 : Technological possibilities for T-sensors, flow-sensors and heaters

Requirements are:

- Very good temperature resolution as ΔT across the TIM will be small (of the order of 0.1 K)
- Compatible with adhesives, greases and metal TIMs
- Surface enhancement on Cu, Au finishes
- Integration of heater and T-sensors and passivation
- T-sensor structures that can also be used as flux sensors.

Therefore different technological processes could be eligible:

Processing possibilities:

- Sputtering of seed layers (TiW, TiPt)
- Application of sputtered or electroplated conductive metal layers (Au, CrNi, Al)
- Structuring for redistribution (Litho)
- Passivation layers (polymer, CVD Oxide, glass?)
- Curing of polymers

ρ [$10^{-6} \Omega\text{cm}$ at RT]:	Ag 1.6,	Cu 1.7,	Au 2.2,	Al 2.7,	Pt 11.0,	Ni 7.0,	CrNi 110
α [$10^{-3}/\text{K}$]:	Ag 3.8,	Cu 3.9,	Au 4.0,	Al 4.0,	Pt 3.9,	Ni 6.7,	CrNi 0.14

Electrical conductivity and temperature coefficient

Materials especially suited for T-sensors (or flow-sensors by sandwich structure) are Au or Al due to a very high sensitivity. Heater structures can be more effectively designed in CrNi.

The first design of a test-system could look like the one given below. To make up for possible tilt of the die, the heat flow can be also measured by a small T-drop across a calibrated thin-film passivation layer. Four sensors (one in each corner) should suffice to obtain a position dependent flow through the sample. Temperature resolution should be high as the Si layers are thin and the temperature is monitored directly at the interface.

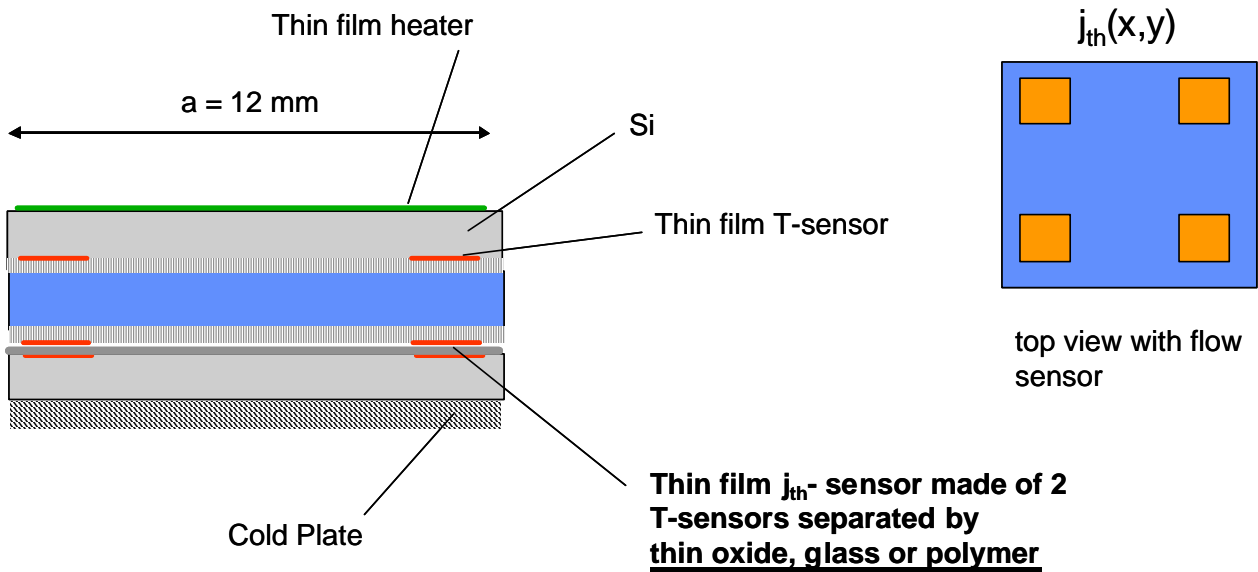


Figure 6 : Improved set-up with best temperature resolution

Challenging here is to integrate metal layers on top of the passivation layers in order to mimic the processes for nano-enhanced surfaces foreseen in WP 3. This may also be done in thin film technology.

A second design is also possible and is given below.

Main advantages are:

- very good planarity, thickness accurately adjustable
- adaptable to modified surfaces
- well suited for adhesives
- Inexpensive and discardable after use, suitable for high-throughput screening

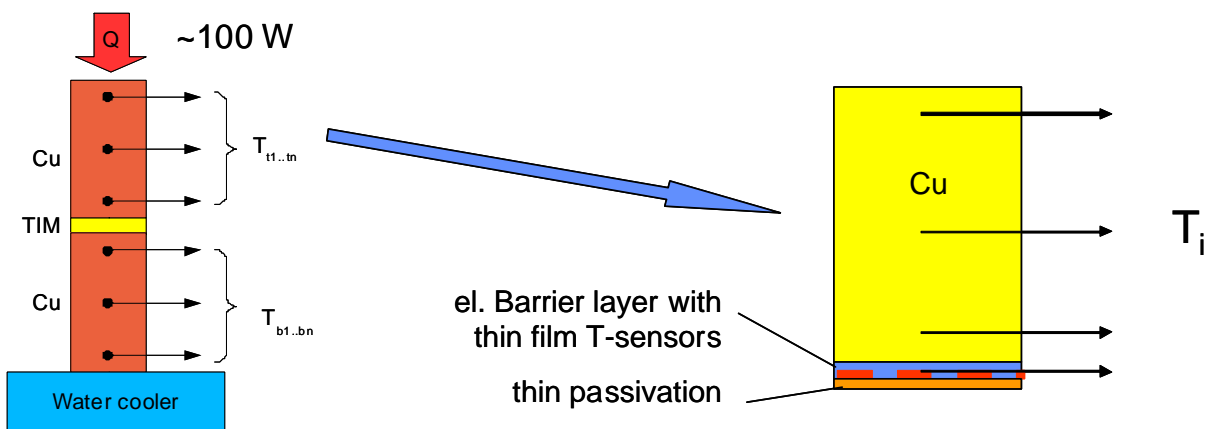


Figure 7 : Improved set-up with best reproducibility and possibilities for surface enhancement

Disadvantage is a not so good accuracy, as heat flux measurement needs a high temperature delta within the Cu blocks.

The Thinfilm Test Structure

The heating structure could have 2 or 4 ports with high resistivity and low TCR, whereas the temperature sensors must have 4 ports for probing and should show a low resistivity and high TCR.

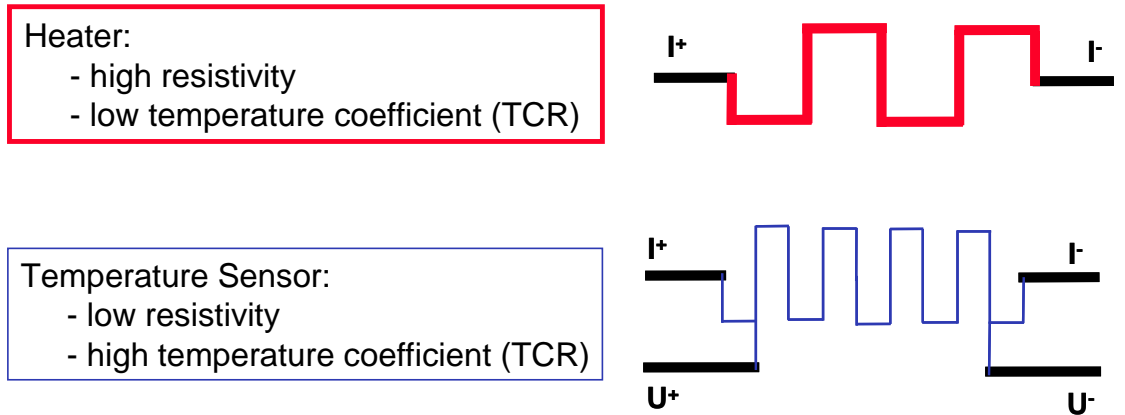


Figure 8 : Possible structure for heater (2-point) and temperature sensors (4-point)

Typical values for resistivity and TCR are given for some thinfilm metals. The material should also exhibit corrosion and oxidation resistance to minimize time and temperature dependent drifts.

Metal	ρ $\mu\Omega\text{cm}$	TCR 1/K
Ag	1,6	0,00380
Cu	1,7	0,00390
Au	2,2	0,00400
Al	2,7	0,00400
Pt	11	0,00390
Ni	7	0,00670
Cr	13	*
NiCr	110	0,00014

Figure 9 : Specific electrical resistivity ρ and temperature coefficient TCR for several metals

Chromium has a non-linear TCR due to its Néel temperature around room temperature which occurs with the antiferromagnetic phase transformation.

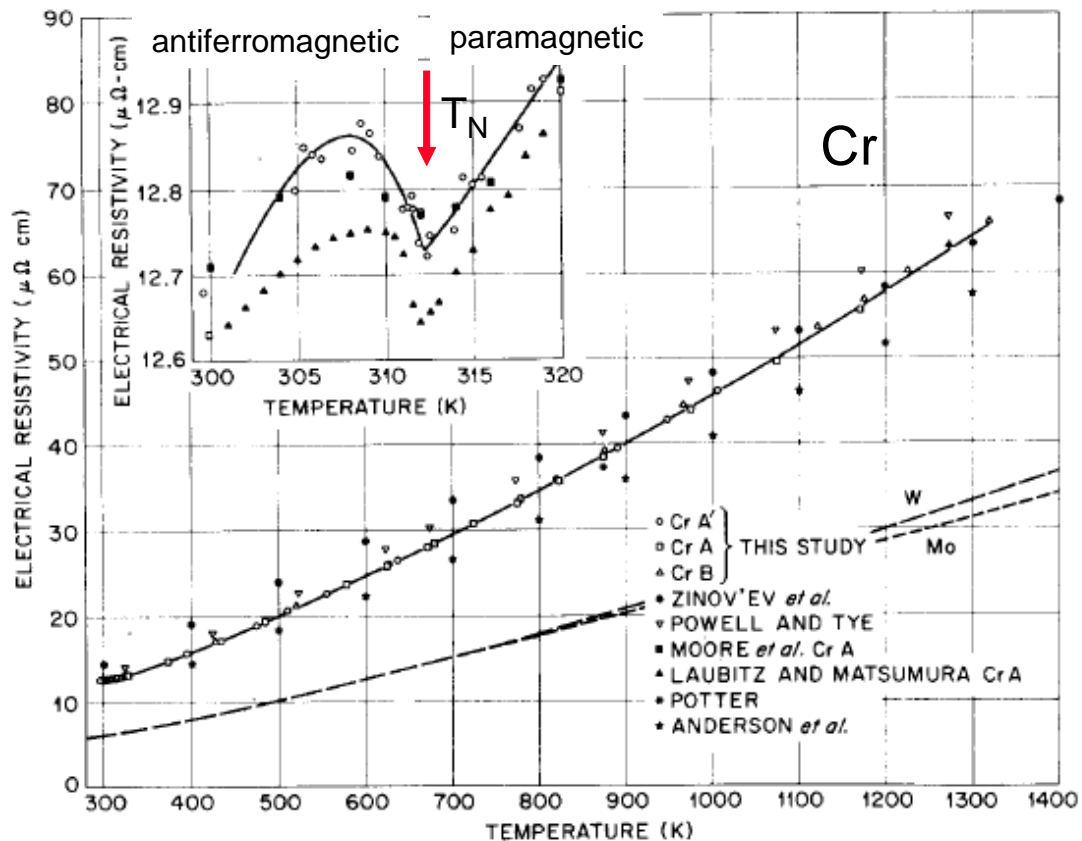


Figure 10: Temperature dependence of electrical resistivity for chromium, tungsten and molybdenum.

NiCr is therefore chosen as heater and nickel as temperature sensor. Preliminary design rules are shown below:

- Heater: ~ 20 nm NiCr**
 - high resistivity
 - 110 $\mu\Omega\text{cm}$ (measured $\sim 100 \Omega/\square$)
 - low temperature coefficient (TCR):
 - $0.14 \cdot 10^{-3} \text{ K}^{-1}$
- Temperature Sensor:**
 - 20 nm NiCr/ 50 nm Ni or
 - 20 nm TiW/ 50 nm Ni
 - low resistivity
 - 7 $\mu\Omega\text{cm}$
 - high temperature coefficient (TCR)
 - $6.7 \cdot 10^{-3} \text{ K}^{-1}$
- Conductor lines: ~ 500 nm Cu**

Figure 11 : Preliminary selected materials for heater and temperature sensors, considered design rule and electrical properties

minimal overlap:

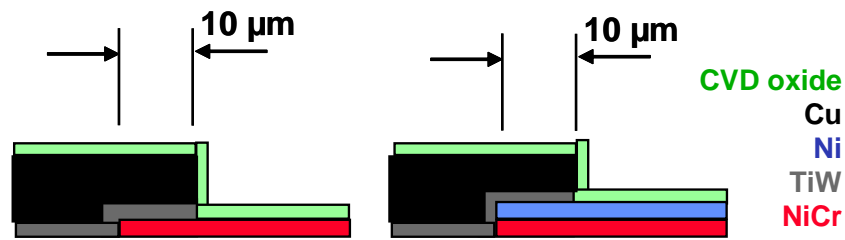


Figure 12: Design schematic

Silicon will be used as a substrate for the thinfilm processes. For the next steps we have to design the test chips. Therefore we need following informations to proceed:

How the test chips will be used?, Chip size and thickness (standard: 670 μm)? Is there a specific back side metallization required to implement the chip into the test configuration?

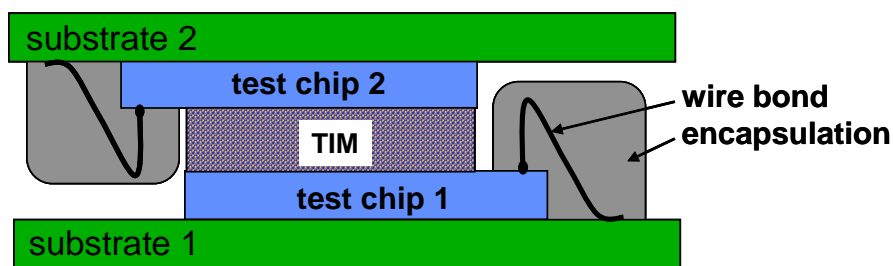


Figure 13: Preliminary sketch of potential test setup

Heater:

- one heating structure on chip only?
- two electrical ports per heater?
- heater on both sides, top & bottom?

Temperature Sensor:

- how many T-sensors per test chip?
- how should they be distributed?
- one current line for all T-sensors?
- 2 voltage sensors per T-sensor

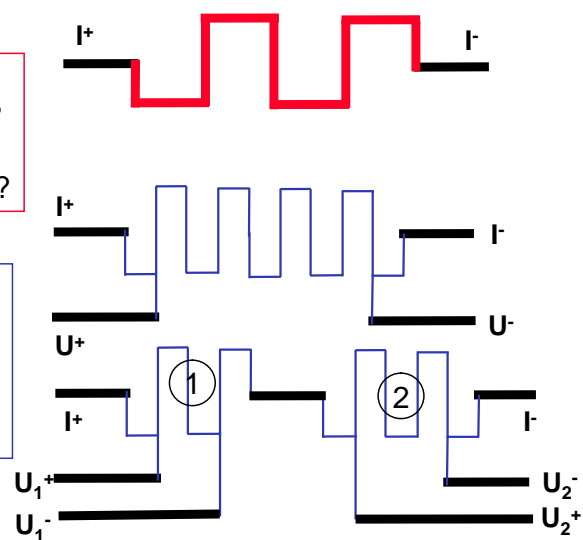


Figure 14 : Schematic of heater and temperature sensor structures.

Realization the interconnect scheme of test chips to outside should be realized? wire bonding? Flex substrate interconnect?

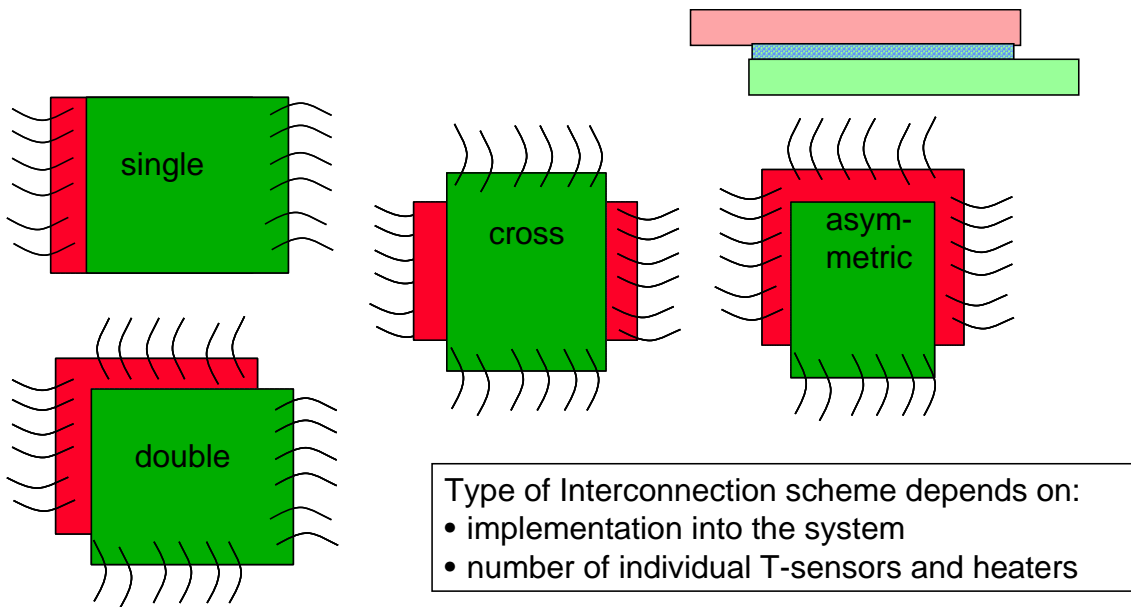


Figure 15 : Potential interconnection schemes

Which power and temperature should be targeted?

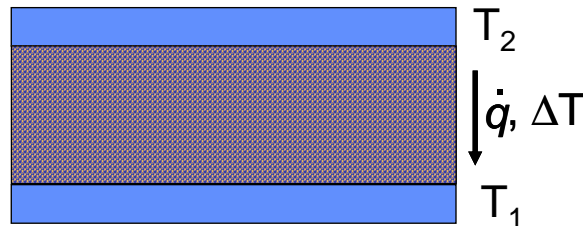


Figure 16 : Schematic of measurement setup: Thermal flow density and expected temperature drop

All open points will be closed in the next steps to continue the design work.

4.4 DEVELOPMENT OF THIN GAP SQUEEZE ASSEMBLY STANDS (CHALMERS, FOAB, EVAC, NANOTEST, TRT)

Nanotest will do material characterization on the nano scale. Tested materials will be analyzed by Focused Ion beam cuts to achieve particle distribution maps. In addition methods of mechanical material characterization will be tested at the relevant materials.

4.5 DEVELOPMENT OF A SAMPLE HOLDER DESIGN ESPECIALLY FOR IN SITU THERMAL TRANSIENT MEASUREMENT OF THIN MATERIALS (BME, MICRED, EVAC)

The arrangement proposed by MicReD will serve to assure testing TIM material in real life applications, that is in packages used as die attach between the chip and the package (TIM1) or as TIM2, between the package and the heat sink.

The arrangement is for being applied in thermal transient testing, using the structure function evaluation methodology. [2,3]

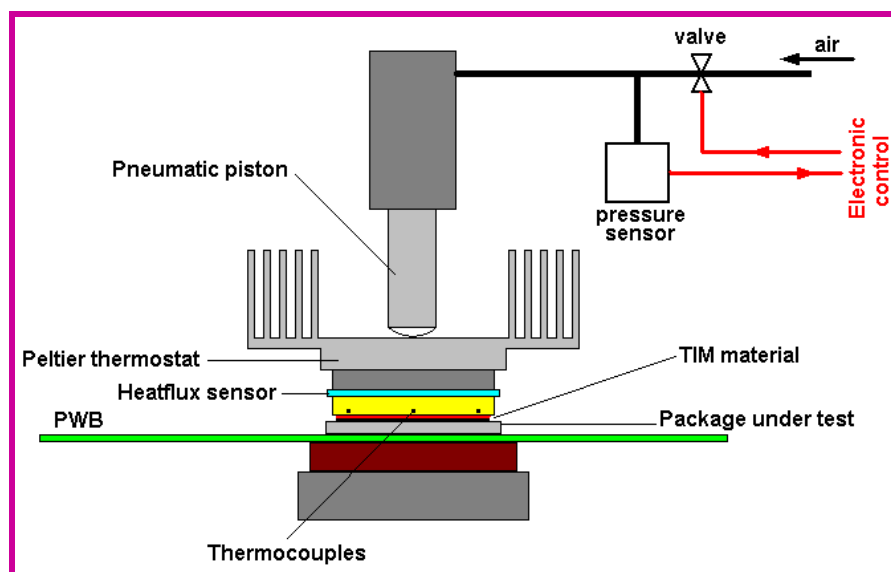


Figure 17: The proposed fixture for real time applications

In this arrangement the both the heating and sensing are assured by the package under test itself.

The thermocouples in the fixture and the heat flux sensor are applied to help the navigation in the structure function.

5 TEST VEHICLES USED AS FINAL DEMONSTRATORS IN WP7

5.1 THAV TEST VEHICLES THAT WILL BE USED FOR THE FINAL EVALUATION IN WP7

Thales Avionics will test the TIM performance in the case of the cooling of an electronic card for the In Flight Entertainment Seat Equipment (IFE). The test vehicle will be a Seat Electronics Box (SEB). The SEB shall supply the passenger seats in the Cabin and beds/seats in the Rooms with audio, video, games, telephone, etc....

There shall be different SEB types corresponding to the required hardware, which is needed to accommodate the requested functions. The SEB type supporting all functions shall have the capability of supplying a minimum of three passenger seats, which necessary for a triple seat-group (may be reduced to two for double seat).

The demonstrator will be made from a SEB having the following sizes:

Length = 292mm, Width = 200mm and Thickness = 45mm

The SEB contains 2 PCBs with dissipative components.

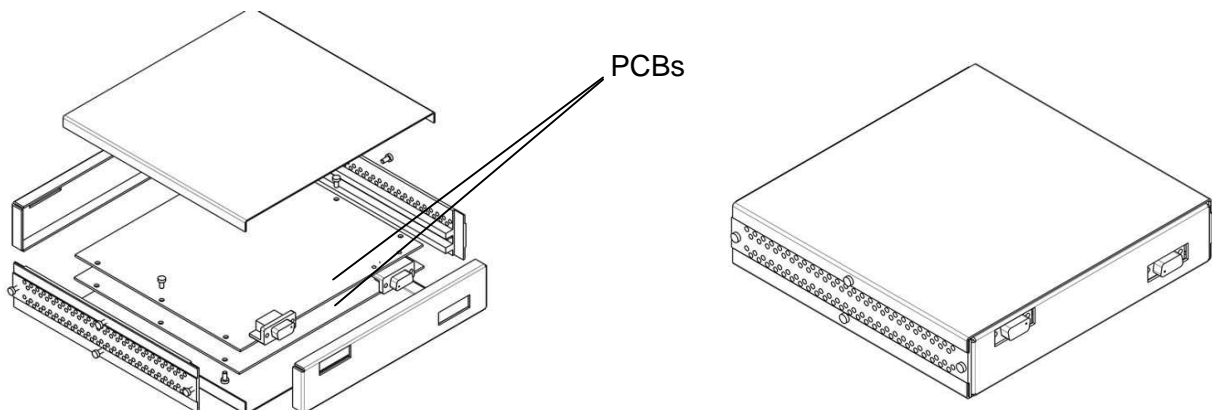


Figure 18 The final demonstrator used by Thales

PCB description

- Material: FR4,
- Considering that the heat dissipation can reach 100 Watts, the PCB internal structure contains 2 copper layers of 35 μm thickness,
- In order to improve conduction heat transfers from the PCB to the SEB, the PCB edges zones are metallised and linked for one hand to the internal layers and for the other hand to the covers.

The SEB demonstrators are integrating 2 types of components:

- Thermal chips, encapsulated in enhanced thermal packages and used for heat generation and temperature measurements (PMOS4),
- Passive components (resistors TO220) for heat generation only.

Thermal chips

The PMOS4 test chips, is a general purpose package performance monitoring test chip which contain test structures to evaluate the following IC package performance parameters:

- Environmental reliability in terms of corrosion of on-chip metallization,
- Thermo-mechanical reliability in terms of:
 - stress induced resistance changes in silicon-based diffused resistors
 - stress induced metal shift in on chip metallization,
- Thermal resistance between the chip surface and some external reference temperature on the IC package, circuit board or the ambient air.
- Temperature of the component junction.

The main die specifications for PMOS4 are listed inTable 2.

	PMOS4
Die size	5 x 10 mm ²
Die pitch	5.1 x 10.1 mm ²
Thickness	500 μm
Scribe channel width	100 μm
Total I/O pads	117
I/O pad size	100 microns square
I/O pad pitch	200 μm
Passivation window opening over I/O pads	90 μm

Table 2: Encapsulated dies specifications

Thermal chips

PMOS4 is 5 mm x 10 mm test chip containing the following items :

- 1 passivated corrosion monitor, covering approximately half of the die,
- 1 heater resistor (300 Ω), covering 85 % of the die
- 3 temperature sensing diodes, located at the center, corner and edge of the die,
- 6 * 3-leg strain gauges, P-doped diffused resistors,
- daisy chain wire bounded structures,
- metal shift patterns.

Thermal characterization is performed using on-chip heater resistors used to supply large power to the chip, combined with p-n junction diodes used for on-chip temperature measurements. The equivalent electric scheme is shown below: there is no electrical common point between the heater circuit and the diode measurement loop. In order to make precise measurements, diodes must be preliminary calibrated.

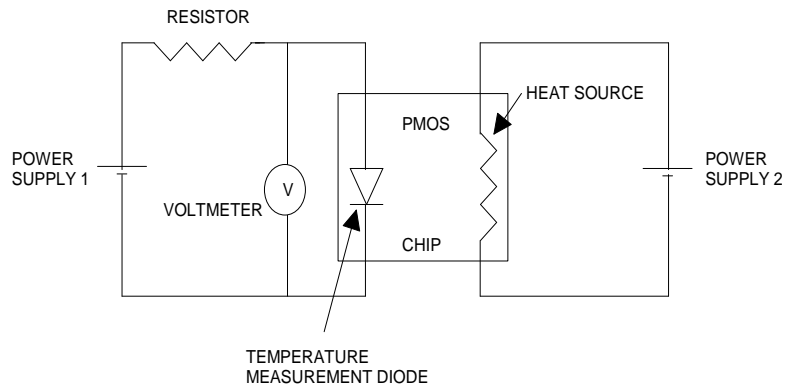


Figure 19 : Electrical scheme for chip management

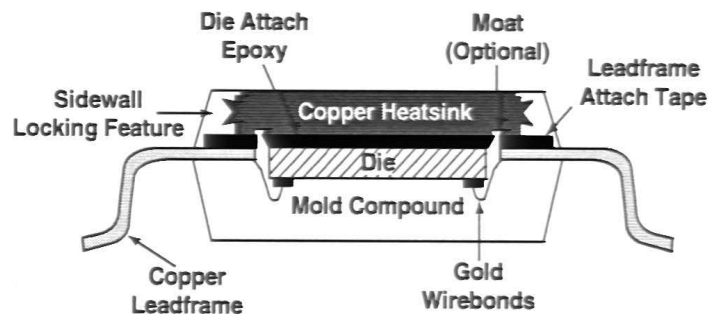
The encapsulation of the thermal test chips is a : Power Quad Flat Pack (QFP 208) for the PMOS4 die.

Power Plastic Quad Flat Pack 208 (PQFP 208)

Power Plastic Quad Flat Pack 208 (All dimensions in mm)					
Lead count	Body size	Total size	Pad size	Body thickness	Stand-off
208	28 x 28	30 x 30	0.5	3.90 max.	0.10 min.

2 PMOS4 are encapsulated in this Power Quad Flat Pack, e.g. a total surface of "active" chip corresponding to 100 mm². Compared to a standard plastic QFP, the power PQFP is integrating in its constitution an aluminium thermal slug that permits to reach powers like 4 to 5 Watts.

Chip-up or chip-down orientation could be obtained by bending the leads in the adequate direction.



Source: Amkor Anam/ICE, "Roadmaps of Packaging Technology" 22083

Figure 20: Thermally enhanced PQFP with embedded heat spreader

Passive components: RT020 resistor

RT0 20 resistors are used to produce the heat additionally to the thermal test components. They consist in a thick film surface mounted medium body with maximum power dissipation of 20 W each, supplied in TO-220 packages and implemented on the active side of the demonstrator PCB.

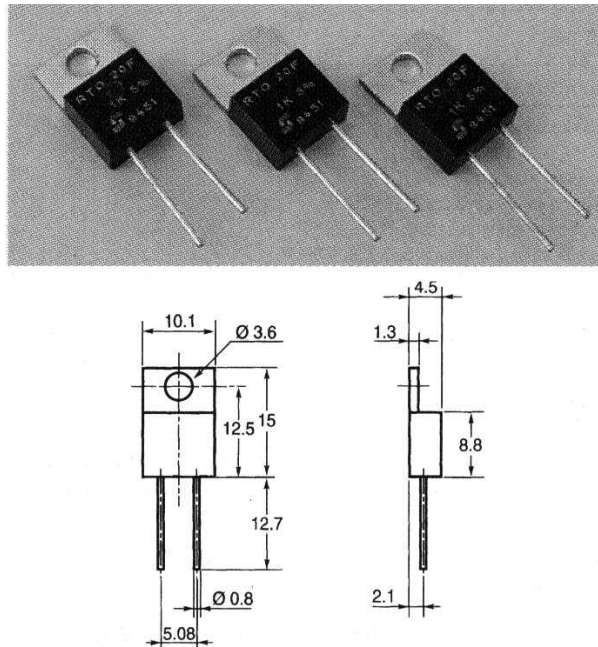


Figure 21: The RT020 resistor

SEB Cooling methods

There are several ways, depending of the thermal dissipated power, which can be used for the cooling of the SEB. In the case of low power, the cooling can be made with air natural convection. But if the power is too high, the cooling system must be improved using heat pipe (HP) or loop heat pipes systems (LHP) (see the following figure).

Heat Pipe and Loop Heat Pipe are two phases heat transfer systems which allow to transfer heat between two points with a high efficiency. On the following figure, heat pipe allow to transport heat between the dissipating component and the SEB wall whereas Loop Heat Pipe extract the heat from the SEB wall to an external heat sink (not represented).

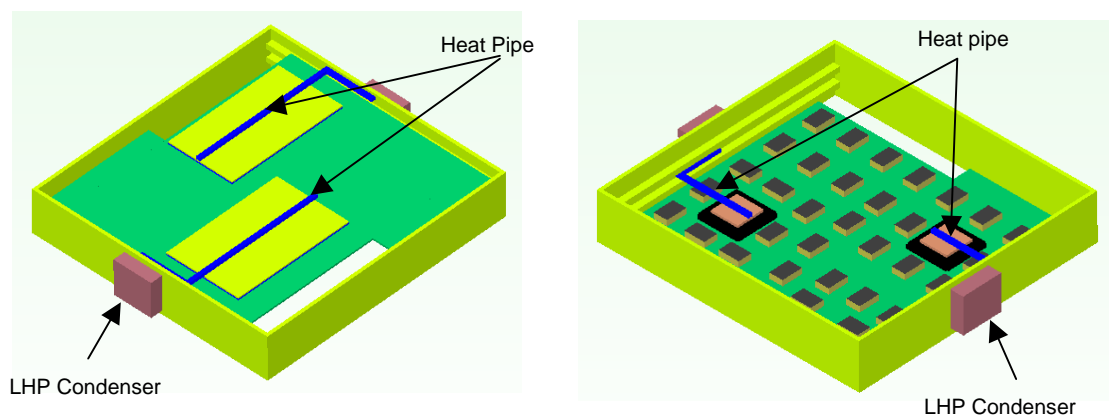


Figure 22: SEB cooling with Heat Pipes and Loop Heat Pipes

These cooling systems need the use of Thermal Interface Material in order to ensure a good thermal contact between each part of the thermal path.

Some of the mounting characteristics are given below :

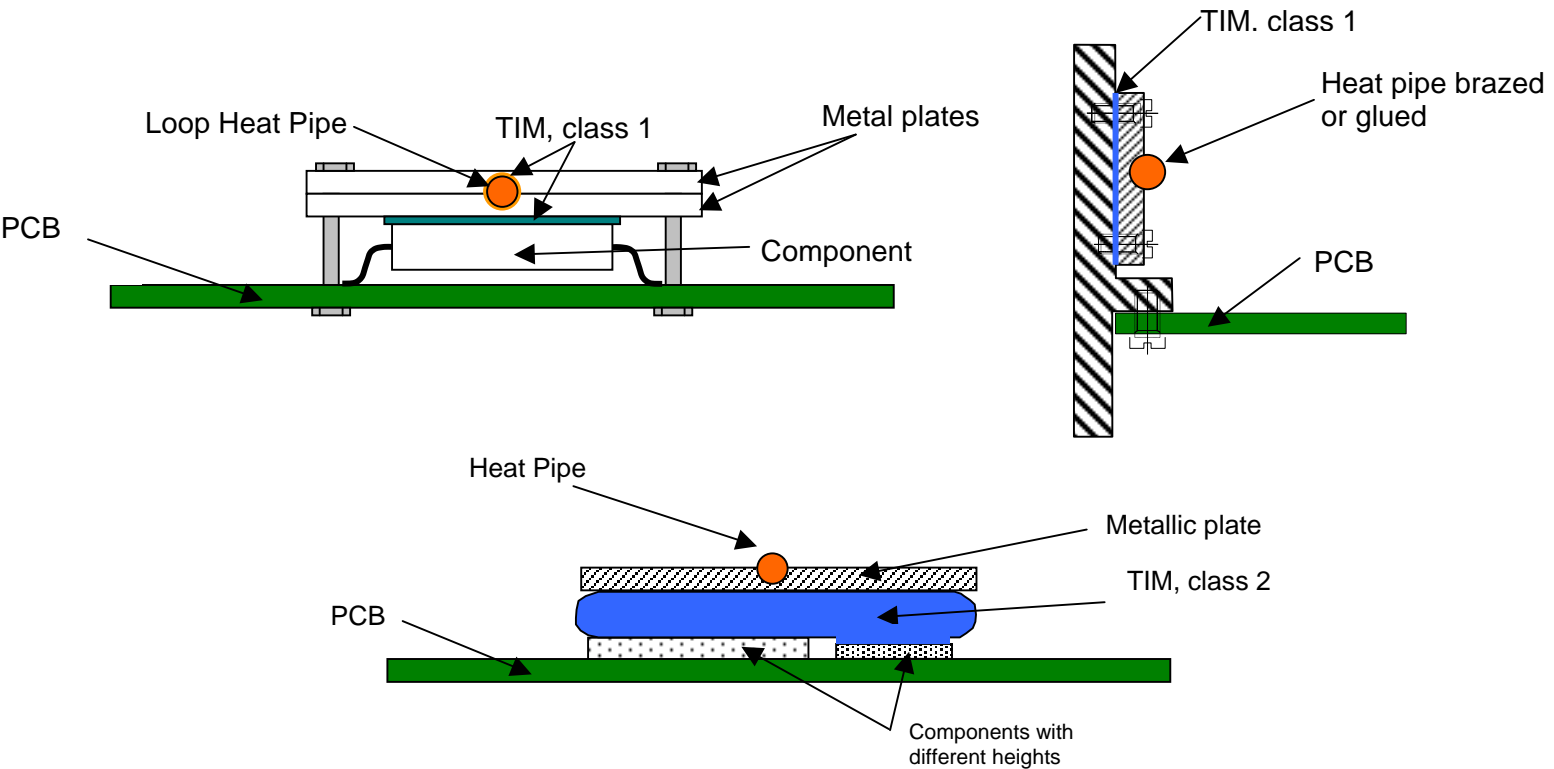


Figure 23: Mounting on the heat pipes

5.2 IBM MICROPROCESSOR TEST VEHICLES

IBM will demonstrate the optimum performance of thermal interfaces developed in NANOPACK using a test vehicle that resembles a high end microprocessor on a ceramic or organic substrate as shown in Figure 24. The package thermal resistance will be measured using the sensors on the lower side of the chip with C4 solder ball array and a thermocouple mounted in the chip lid or heat sink base if a direct attach heat sink application is desired at the time of testing.

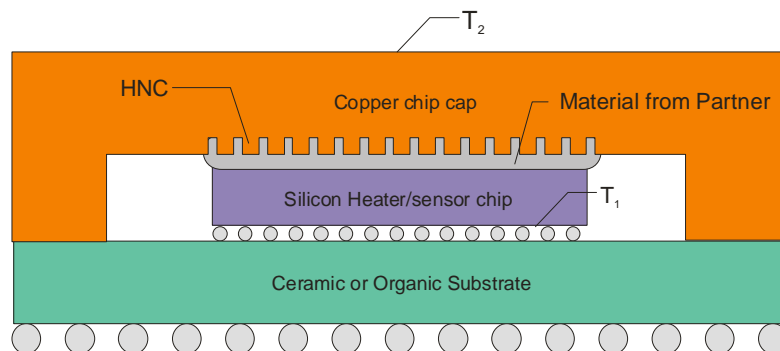


Figure 24 : Microprocessor Test Vehicle used to estimate TIM performance in application environment.

5.3 BOSCH TEST VEHICLES THAT WILL BE USED FOR THE FINAL EVALUATION IN WP7

Bosch will test TIM performance by benchmarking thermal resistance of newly developed materials and processes against thermal performance of an existing product. We chose an electrical control unit with integrated high power circuits as given in the figure below.

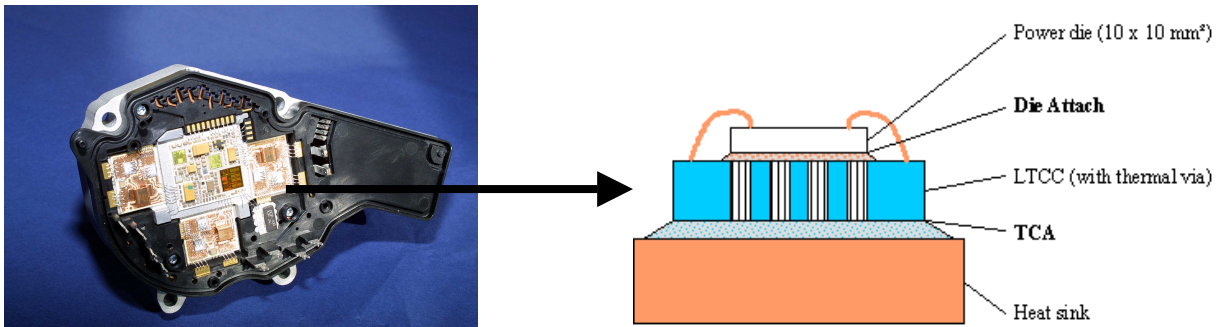


Figure 25 : Electrical control unit with logic circuit (centre) and three surrounding power circuits

The logic circuit in the centre of the control unit is based on LTCC substrate. TIM2 would have to be electrically isolating therefore. But, thermal loss of logic circuit is quite low and is not addressed in NanoPack, therefore. The surrounding power circuits are based on DBC (direct bonded copper substrate). As DBC provides electrical isolation between upper side and lower side, TIM2 does not need to be electrically isolating.

We will test thermal performance of DBC substrate with 2 soldered diodes on top connected to a heat sink.

5.4 TRT TEST VEHICLE

The RF-MEMS capacitive switch relies on a metal planar membrane suspended over the central line of coplanar waveguide, and resting on its ends on the ground lines. An electrode and a dielectric are integrated in the signal line. When a DC voltage is applied between this electrode and the metal membrane, this latter is deflected downwards due to electrostatic forces. In the un-actuated state, the membrane presents a high impedance with respect to the line, and the signal is unaffected. In the down position, the membrane is capacitively coupled to the bottom plane, and short-circuits the signal to the ground.

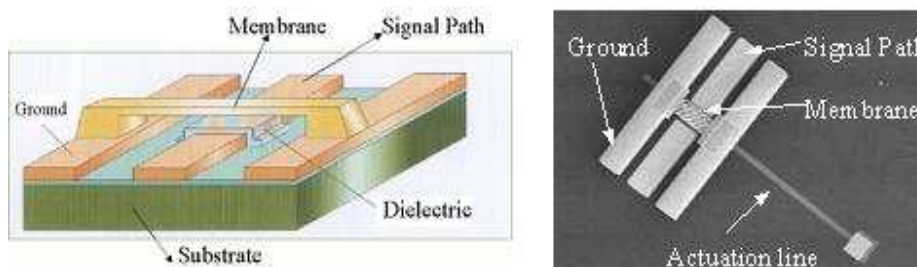


Figure 26: Non packaged RF-MEMS capacitive shunt switch

RF-MEMS switches are collectively micromachined on Si or GaN/AlGaN wafers, in 9 photolithographic levels:

- 1 - Bottom electrode patterning
- 2 - High-k dielectric definition,
- 3 - Signal line & pad definition,
- 4 - High value resistor definition,
- 5 - Passivation openings (vias),
- 6 - Line & pad definition,
- 7 - Seed layer local etching
- 8 - Line & pad gold plating,
- 9 - Membrane definition

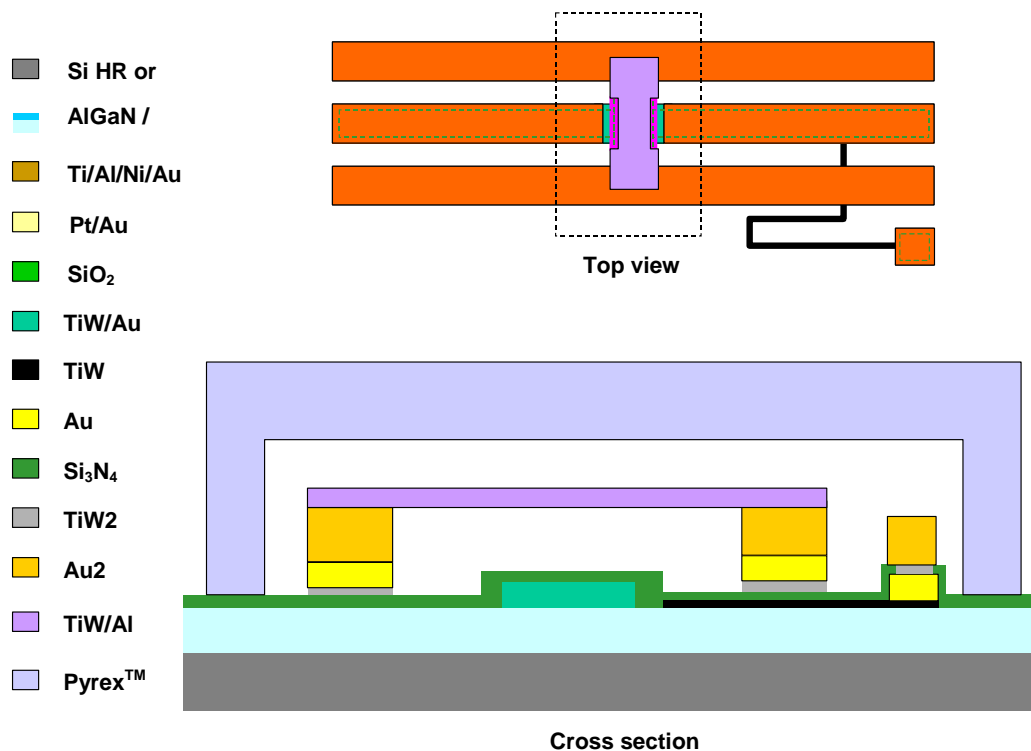


Figure 27: Topology and materials used for RF-MEMS capacitive shunt switch

In order to protect brittle membranes of switches, a mechanical protection is necessary. A Wafer Level Packaging method is used, with a structured Pyrex™ cover, that is polymer attached on the top of each chip. A specific micro-positioning bench is used in order to pick the cover, to precisely align it with the chip to protect, to stamp it in a controlled thickness glue and finally to place it on the chip. Polymer curing is done collectively in an oven after all the covers have been placed. Die separation is done by backside pre-cutting.

Process flow is the following :

- 1 - 100mm Pyrex™/Si wafer anodic bonding
- 2 - Silicon thinning up to 100µm
- 3 - Wall & cavity lithography (with sizing that take account Pyrex™ undercutting)
- 4 - Silicon etching (Pyrex™ cover wall and cavity definitions)
- 5 - Pyrex™ HF etching (50µm to 100µm)
- 6 - Si KOH removal

7 - Saw dicing (cover die separation)

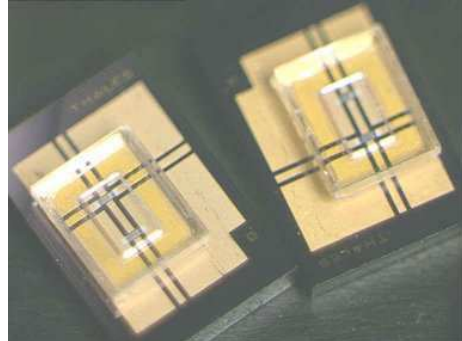
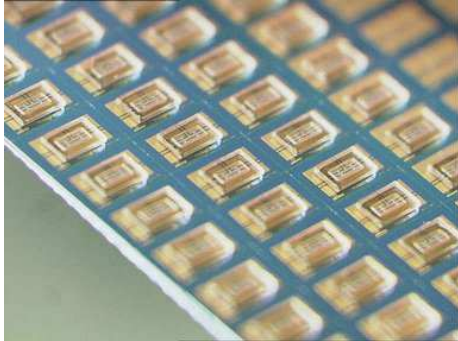


Figure 28: Figure: Images of packaged RF-MEMS switches, before and after die separation

6

CONCLUSION

This report has defined the test specimen and test system which will be used in **WP4 (Design and fabrication of test structure)** T0+6 -> T0+30.

The objectives of WP4 are :

- To research, simulate, design and manufacture test structures to facilitate the measurement of thin layers of very high thermal conductivity material. As different measurement methods will be used in the consortium, different test conditions have to be elaborated, examined, perfected and finally prepared for standardization
- To develop test structures in order to investigate the electrical properties of micro scale particle stacks for application as electrical interconnects in stacked chip packages

WP4 will explore and manufacture test structures to facilitate the measurement of thin layers of very high thermal conductivity material. As different measurement methods will be used in the consortium different test conditions have to be elaborated, examined, perfected and finally prepared for standardization. WP4 will allow to characterize the thermal interface materials developed in WP2 and WP3 along with their process dependence in their thermal, electrical and thermo-mechanical properties.

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